

Changes in Porous Media Properties by Modeling Dissolution and Morphological Transformations in Micro-CT images

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May 16, 2019

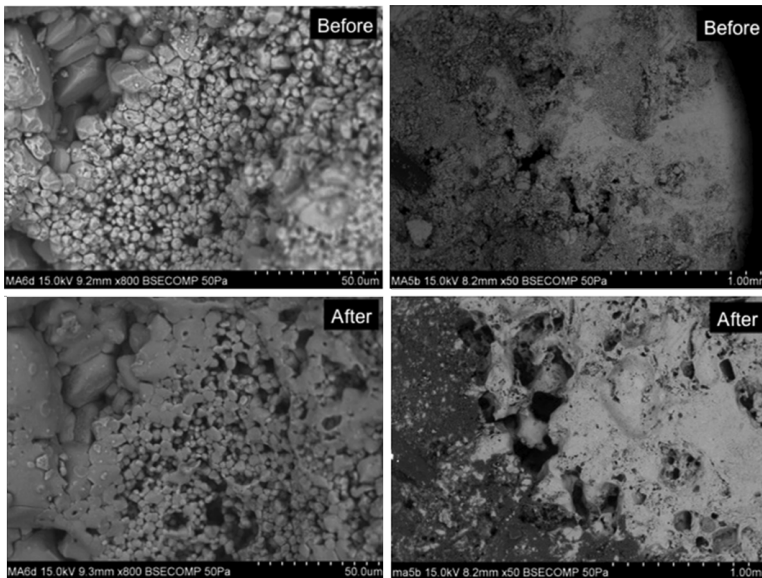


Stanford
University



Dissolution by CO₂ Rich Water

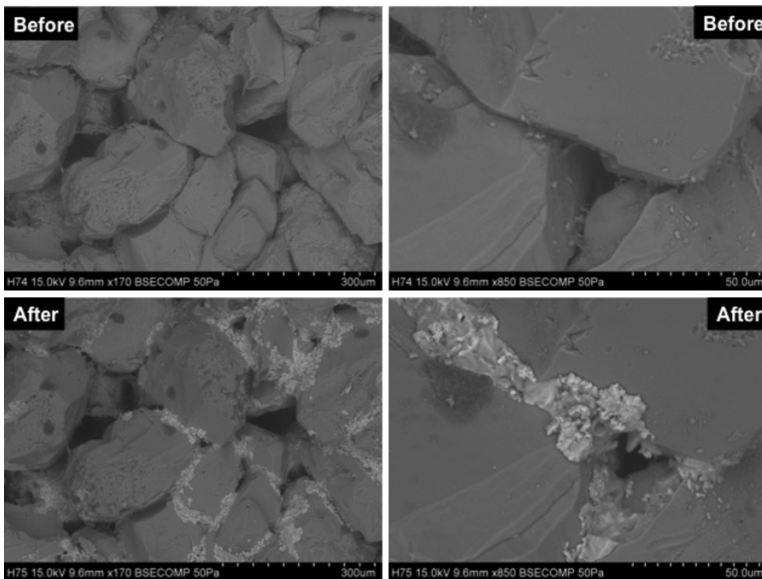
(Vanorio, Nur & Ebert, 2011)





Salt Precipitation

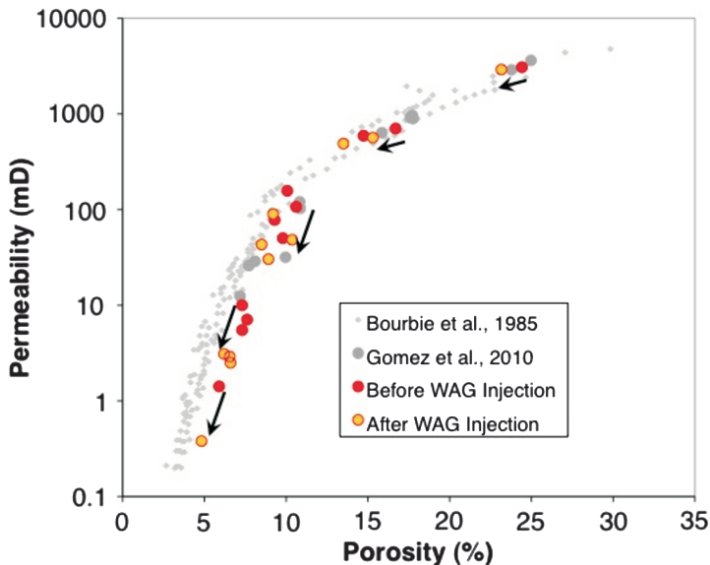
(Vanorio, Nur & Ebert, 2011)





Permeability – Porosity Evolution

(Vanorio, Nur & Ebert, 2011)

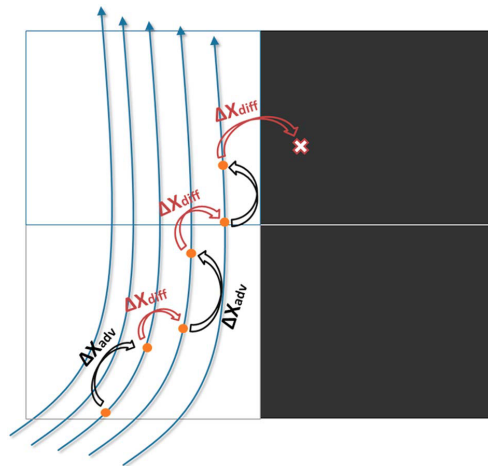
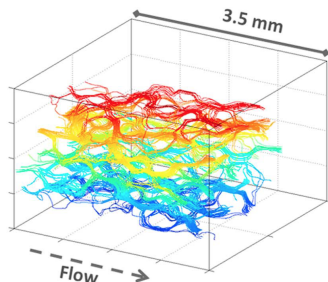




Previous Work

Pore-scale simulation of carbonate dissolution in micro-CT images. Nunes, Blunt 2016.

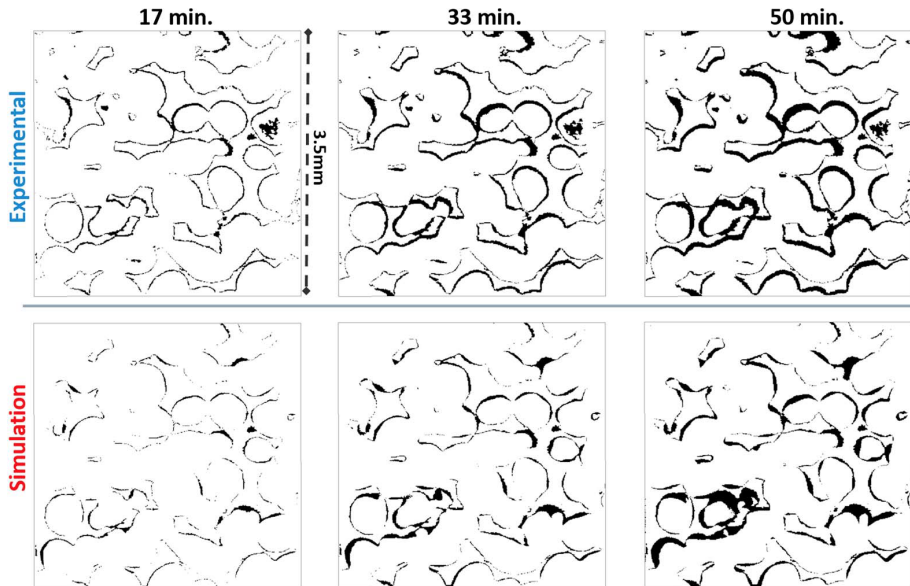
- κ : Navier-Stokes flow model.
- C : Advection-diffusion equation.
- Diffusive term with a random walk.
- Dissolution as particle tracking.
- Dissolution rate, number of particles that hit a voxel, with a threshold ϕ .





Previous Work

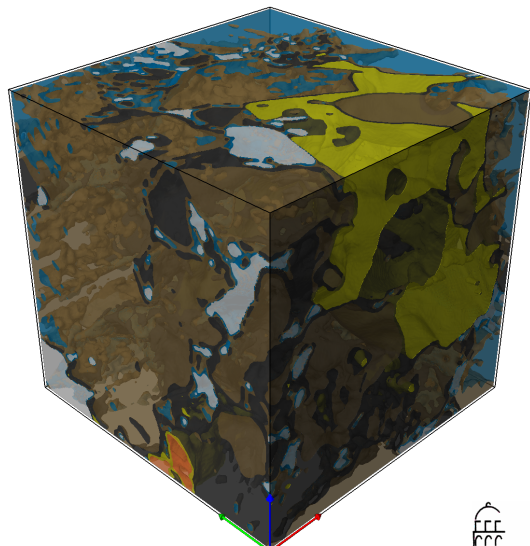
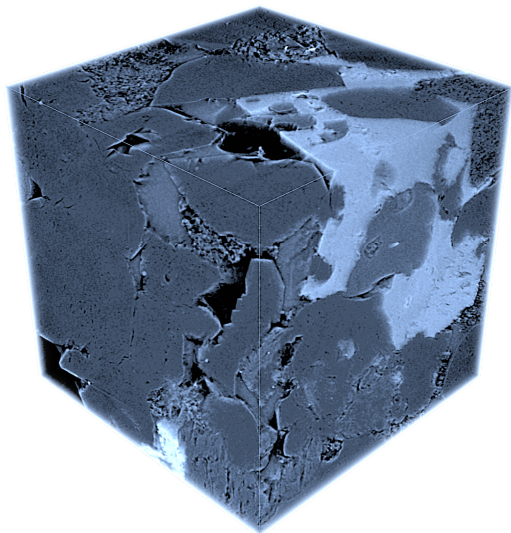
Pore-scale simulation of carbonate dissolution in micro-CT images. Nunes, Blunt 2016.





Micro-CT scan scale

Berea Sandstone $\approx 500\mu\text{m}$

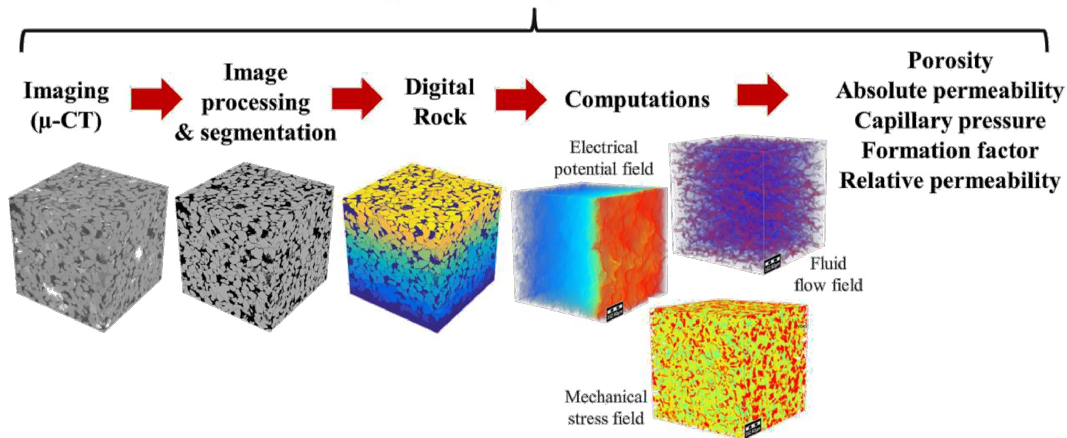




Present processing of CT-scan Data

N. Saxena(2017)

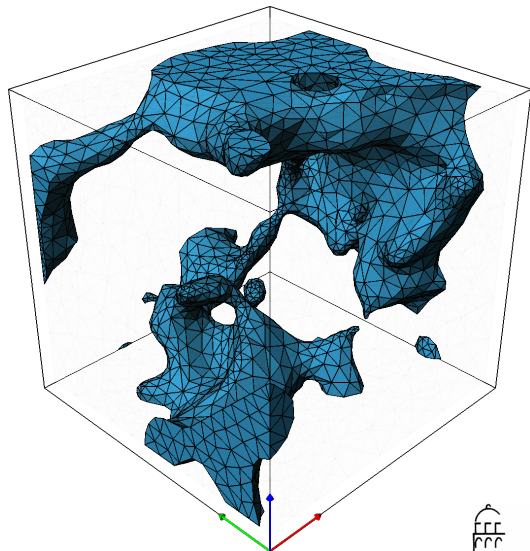
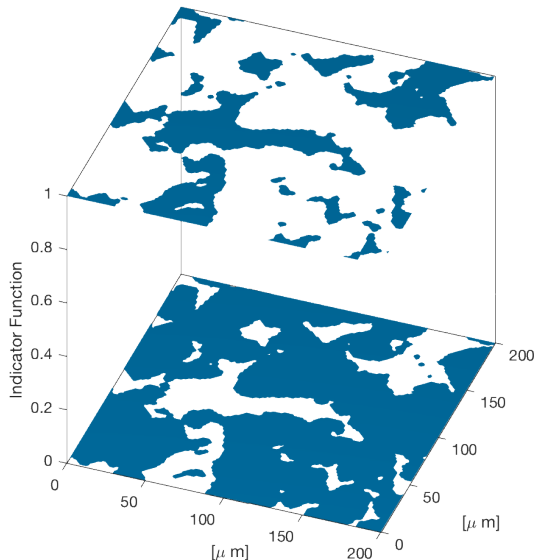
Digital core analysis workflow





Present Rock Geometry Representations

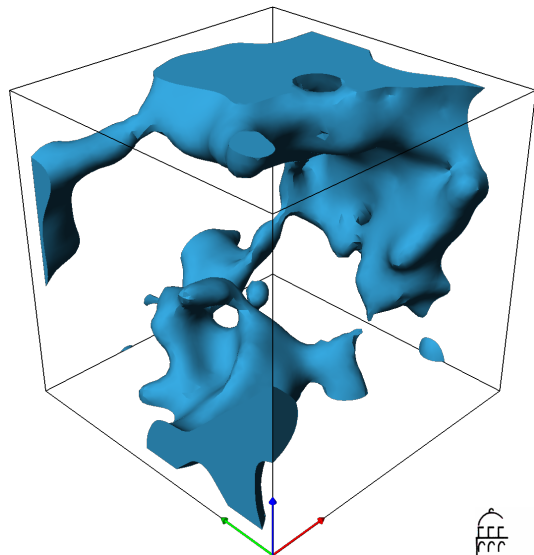
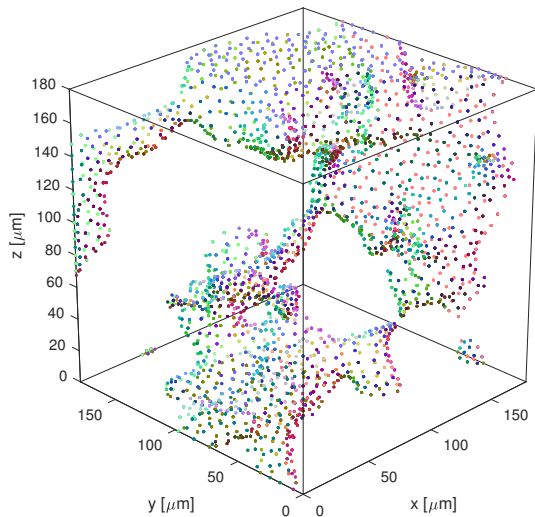
Indicator Function and Tetrahedral Meshes





Other Ways to Express Rock Geometry

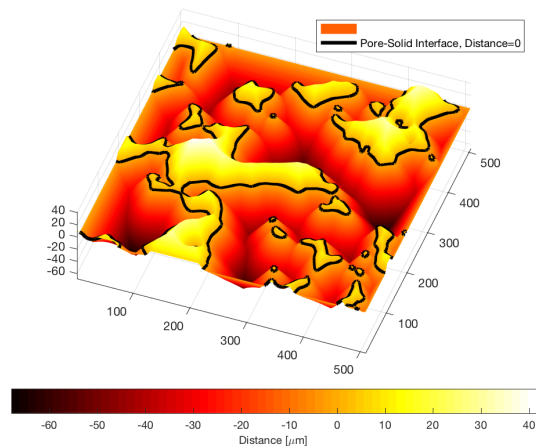
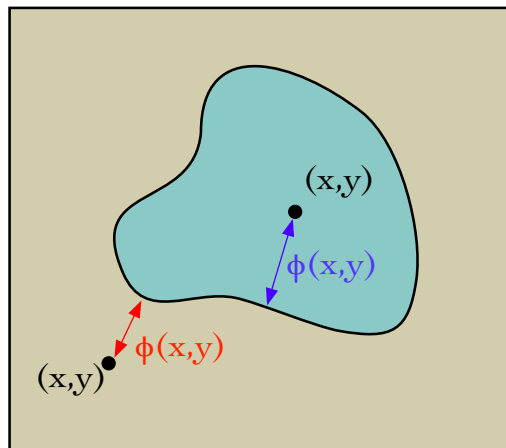
Implicit Functions and Point Clouds





Distance Function

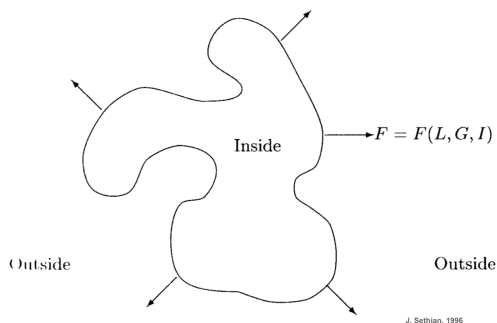
Osher, S., & Sethian, J. A. (1988). *Journal of Computational Physics*, 79(1)





Propagating boundaries

The time view



The boundary value.

- F is the normal velocity field.
- $T(\vec{x})$ arrival time.
- $|\nabla T|F = 1$ with $T = 0$ on Γ



Propagating Boundaries

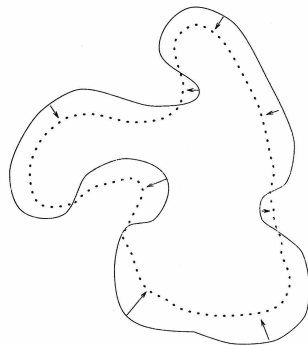
Implicit Function view

Move the boundary with a velocity field $\vec{v}(t)$

$$\frac{\partial \phi}{\partial t} + \vec{v}(\vec{x}, t) \cdot \nabla \phi = 0$$

$$\phi(\vec{x}, 0) = 0$$

- ❑ The solution is not a distance function.
- ❑ The starting function does not need to be a distance function. (Barles, 1993).

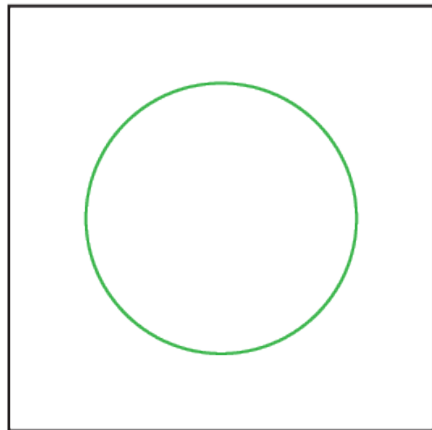




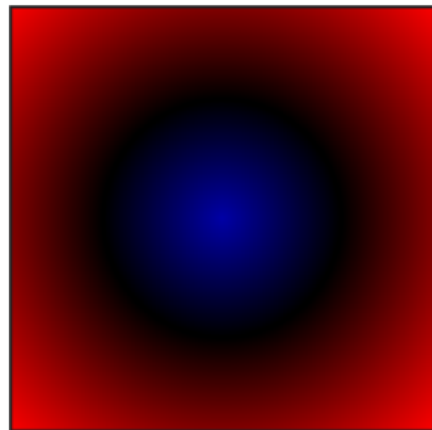
Fast Marching Methods

Using the time view

Input



ArrivalTime



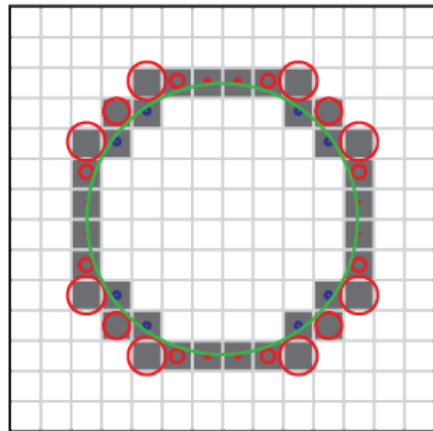


Fast Marching Methods

Using the time view

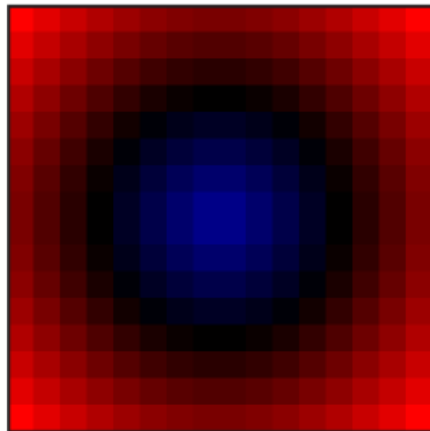
Input

(1,1)



(0,0)

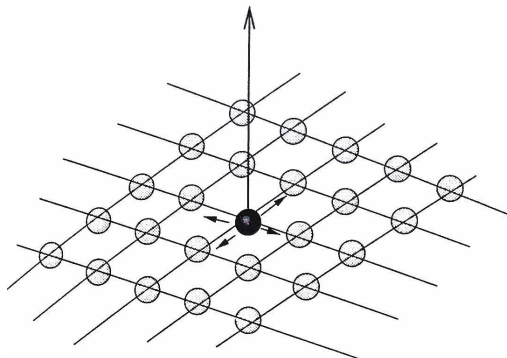
ArrivalTime



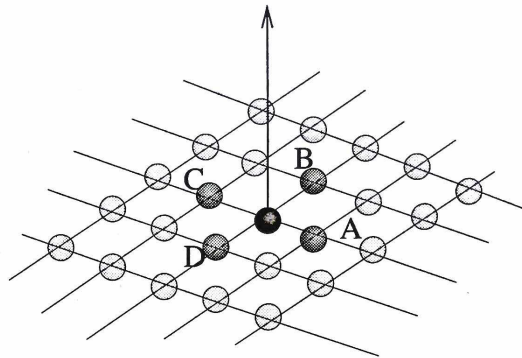


Fast Marching Methods

Using the time view



Update "downwind"

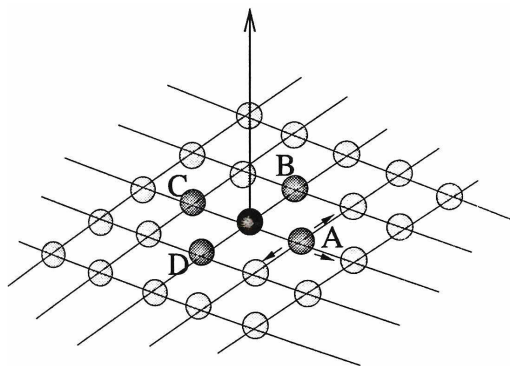


Compute new possible values

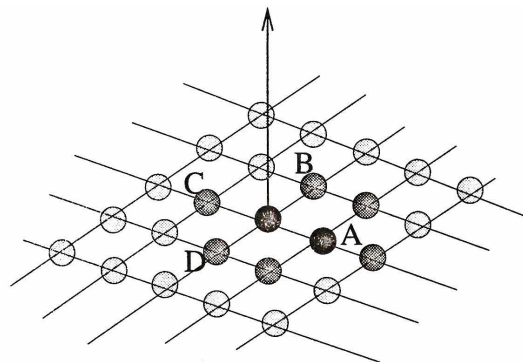


Fast Marching Methods

Using the time view



Choose smallest dark gray sphere
(for example, "A")

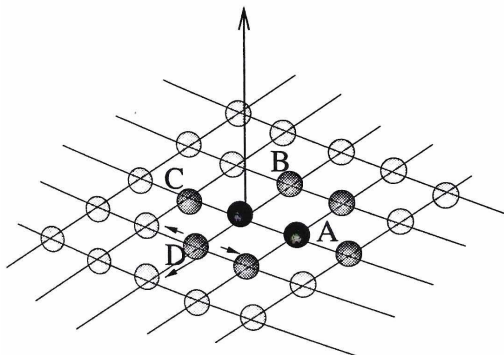


Freeze value at A, update
neighboring downwind points

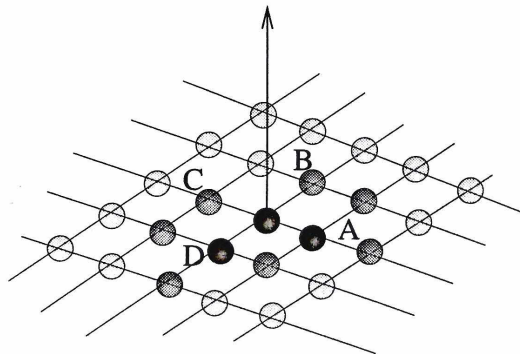


Fast Marching Methods

Using the time view



Choose smallest dark gray sphere
(for example, "D")

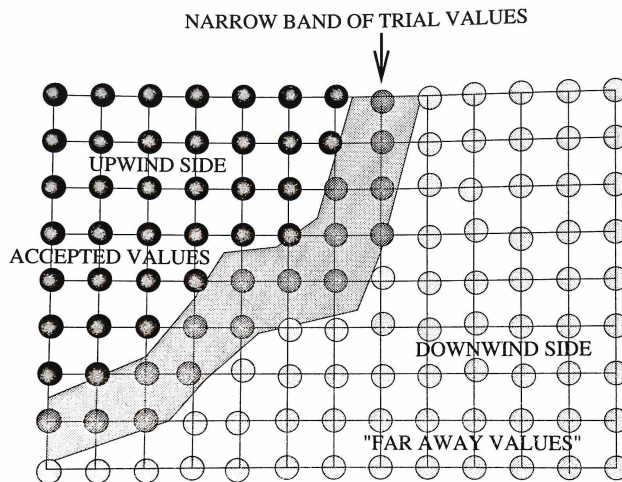


Freeze value at D, update
neighboring downwind points



Fast Marching Methods

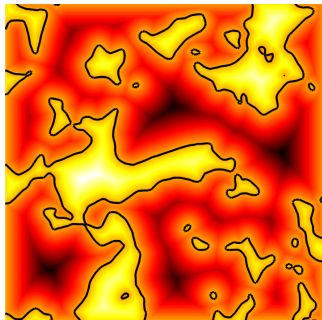
Using the time view





Properties of the Distance Function

- The boundary is clearly defined at the zero distance.
- Unit normal is give by:



$$\vec{N} = \frac{\nabla\phi}{|\nabla\phi|}$$

- The mean curvature is given by:

$$\kappa = -\nabla \cdot \left[\frac{\nabla\phi}{|\nabla\phi|} \right]$$

- The indicator function is readily available.
- The norm of the gradient is one:

$$|\nabla\phi| = 1$$



Moving the boundary

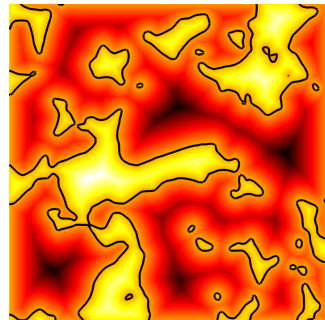
Osher, S., & Sethian, J. A. (1988). *Journal of Computational Physics*, 79(1)

Move the boundary with a velocity field $\vec{v}(t)$

$$\frac{\partial \phi}{\partial t} + \vec{v}(\vec{x}, t) \cdot \nabla \phi = 0$$

$\vec{v}(\vec{x}, t)$ Can be defined as a function of the processes present.

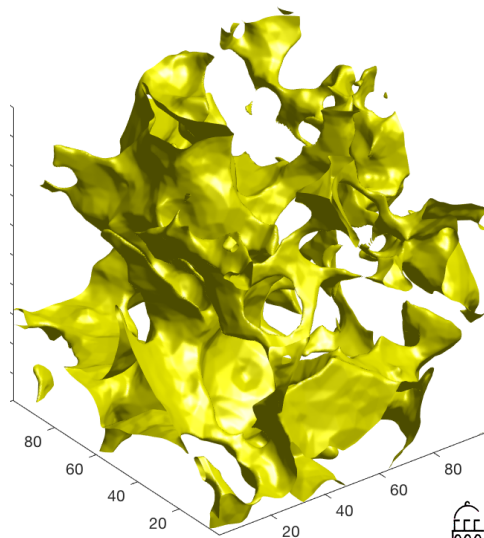
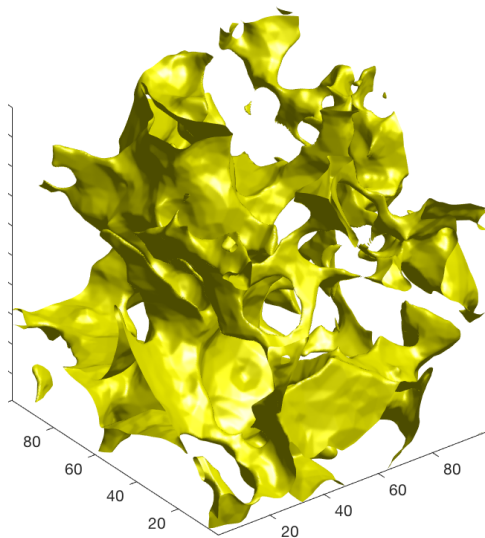
- The solution is not a distance function.
- The starting function does not need to be a distance function. (Barles, 1993).





$$\vec{v} = \pm c \hat{n}$$

Dissolution and Deposition, Berea Sandstone 200 μ m



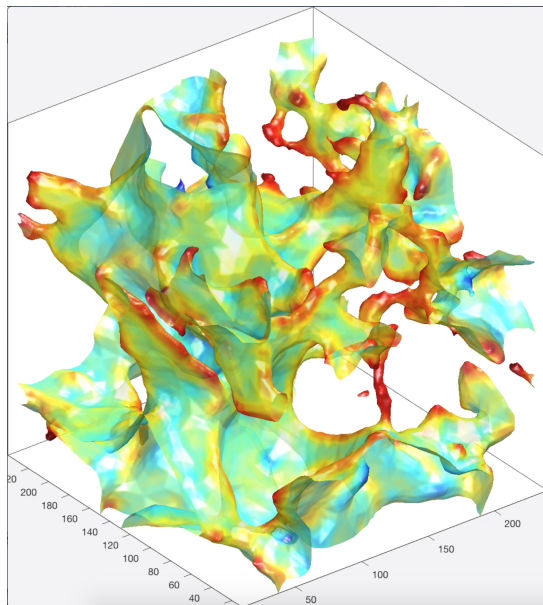


Advection by Surface Curvature

$$\frac{\partial \phi}{\partial t} + \vec{v}(\vec{x}, t) \cdot \nabla \phi = 0$$

$$\vec{v} = - \left(\nabla \cdot \left[\frac{\nabla \phi}{|\nabla \phi|} \right] \right) \hat{n}$$

- Surface curvature is implicit in the chemical potential (*Miller 2016, Personal Communication*)
- Berea Sandstone
200 μm



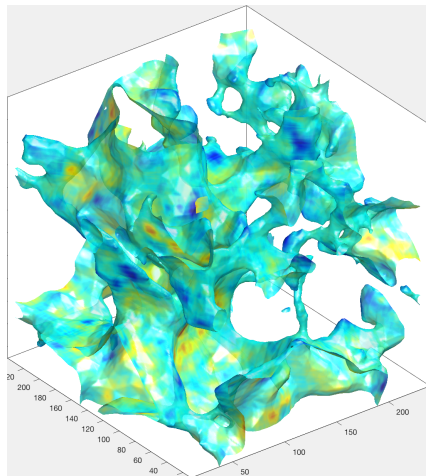


Surface Diffusion

- ❑ Preserves volume.
- ❑ Destroys the distance function.
- ❑ Fourth order derivative, unstable.
- ❑ Implicit in space, explicit in time.
- ❑ Destroys the distance function.

$$\vec{v} = \nabla_s \kappa \hat{n}$$

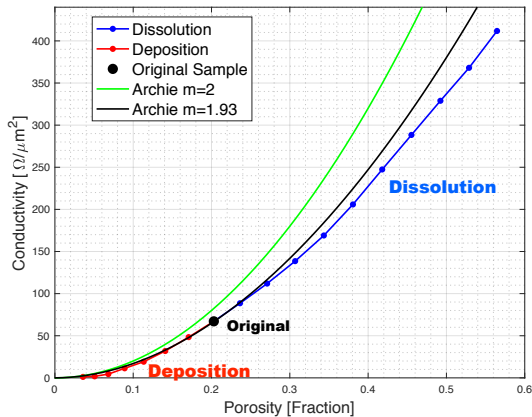
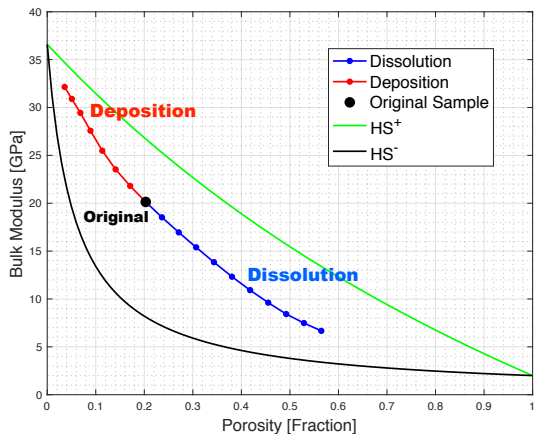
$$\vec{v} = (\nabla - \partial_n) \cdot (\nabla - \partial_n) \left(\nabla \cdot \left[\frac{\nabla \psi}{|\nabla \psi|} \right] \right) \hat{n}$$





Elastic and Electrical Properties

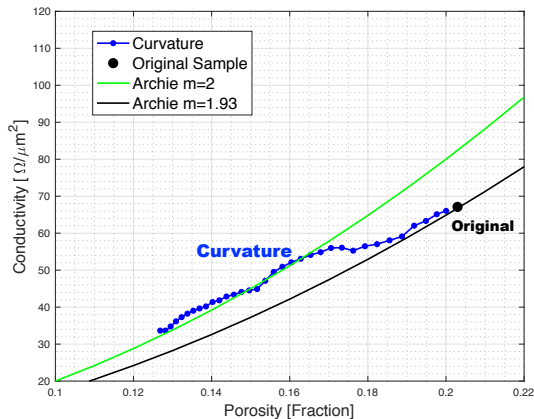
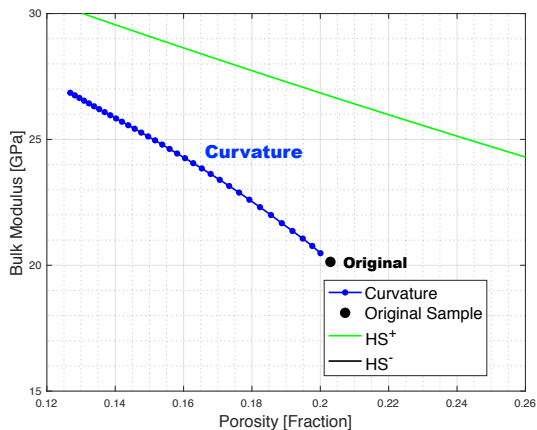
Motion at Constant Velocity





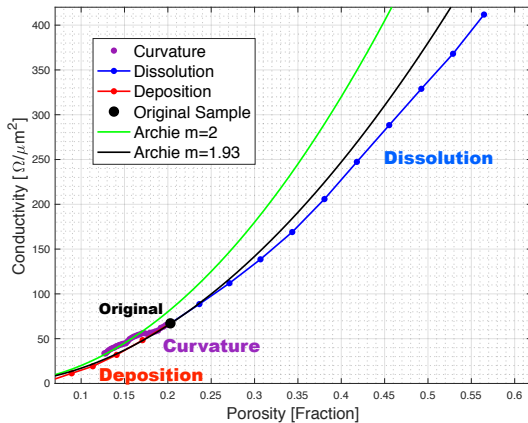
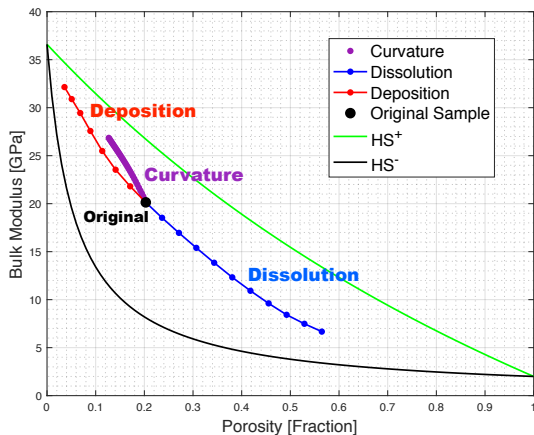
Elastic and Electrical Properties

Motion proportional to Curvature





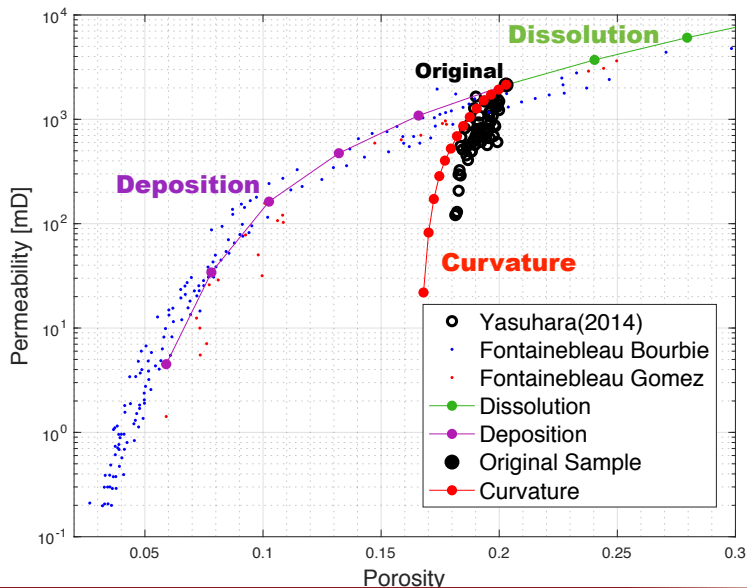
Elastic and Electrical Properties Comparison





Transport Properties

Motion proportional to Curvature





Future Work: Processes Present

Fluid Flow, Dissolution, Stress

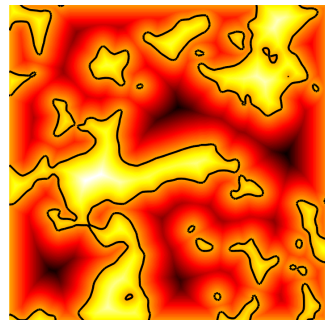
$$\vec{v}(t) = \vec{v}(\vec{v}(\vec{x}, t), C(\vec{x}, t), \sigma(\vec{x}, t))$$

Where:

- $\vec{v}(\vec{x}, t)$ is the fluid flow field.
- $C(\vec{x}, t)$ is the chemical process that dissolves the rock.
- $\sigma(\vec{x}, t)$ is stress.

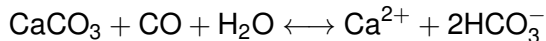
In more detail:

- $C(\vec{v}(\vec{x}, t), t)$
- $C(\vec{v}(\vec{x}, t), \sigma(\vec{x}, t), t)$





Future Work: Dissolution $C(\vec{\nu}(\vec{x}, t), t)$



Diffusion, Advection

$$P_e = \frac{d v_{df}}{D}$$

Advection, Dispersion

$$P_{e,D} = \frac{L_c v_{df}}{f(D)}$$

Advection, Reaction

$$D_a = \frac{\alpha S_r k(T) L}{C_{eq} v_{df}}$$



$$\frac{\partial C}{\partial t} + \nu \cdot \nabla C = D \nabla^2 C + K_{\text{eff}}(C_{\text{eq}} - C)$$



Conclusions

- With this computational approach it is becoming possible to rigorously simulate pore space diagenesis in rocks.
- Predict the associated changes of rock's physical properties.



Acknowledgments

- Amos Nur
- Gary Mavko
- Ron Fedkiw and David Hyde, Stanford CS Department.
- SRB Affiliates.